# POLYTOPE CONTAINMENT AND DETERMINATION BY LINEAR PROBES

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### ABSTRACT

As the terms are used here, a body in  $\mathbb{R}^d$  is a compact convex set with nonempty interior, and a polytope is a body that has only finitely many extreme points. The class of all bodies whose interior includes the origin 0 is denoted by  $\mathcal{C}_0^d$ . A set X is symmetric if X = -X. The ray-oracle of a body  $C \in \mathcal{C}_0^d$  is the function  $\mathcal{O}_C$  which, accepting as input an arbitrary ray R issuing from 0, produces the point at which R intersects C's boundary. This paper is concerned with a few central aspects of the following general question: Given certain information about C, what additional information can be obtained by questioning the ray-oracle, and how efficiently can it be obtained? It is assumed that the usual arithmetic operations in  $\mathbb{R}^d$  are available at no cost, so the efficiency of an algorithm is measured solely in terms of its number of calls to the ray-oracle.

The paper discusses two main problems, the first of which – the containment problem – arose from a question in abstract numerical analysis. Here the goal is to construct a polytope P (not necessarily in any sense a small one) that contains C, where this requires precise specification of P's vertices. There are some sharp positive results for the case in which d=2 and C is known not to be too asymmetric, but the main result on the containment problem is negative. It asserts that when  $d \geq 3$  and the body is known only to be rotund and symmetric, there is no algorithm for the containment problem. This is the case even when there is available a certain master oracle whose question-answering power is much greater than that of C's ray-oracle. However, it turns out that even when there is no additional information about C, the following relaxation of the containment problem admits

Research of the first author was supported in part by the Deutsche Forschungsgemeinschaft. Research of the second author was supported in part by the Deutsche Forschungsgemeinschaft, the Fulbright-Kommission of Germany, and the National Science Foundation, U.S.A.

an algorithmic solution based solely on the ray-oracle: Construct a polytope containing C or conclude that C's centered condition number exceeds a certain bound.

In the other main problem — the reconstruction problem — it is known only that C is itself a polytope and the problem is to construct C with the aid of a finite number of calls to the ray-oracle. That is accomplished with a number of calls that depends on the combinatoral complexity of C.

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As the terms are used here, a body in  $\mathbb{R}^d$  is a compact convex set with nonempty interior, and a polytope is a body that has only finitely many extreme points. The class of all bodies whose interior includes the origin is denoted by  $C_0^d$ . A set X is symmetric if X=-X. The ray-oracle of a body  $G\in C_0^d$  is the function  $O_G$  which, accepting as input an arbitrary ray R issuing from 0, produces the point at which R intersects G's boundary. This paper is concerned with a few central aspects of the following general question: Given certain information about G, what additional information can be obtained by questioning the rayoracle, and how efficiently can it be obtained? It is assumed that the usual arithmetic operations in R' are available at no cost, so the efficiency of an algorithm is measured solely in terms of its number of calls to the ray-oracle.

The paper discusses two main problems, the first of which – the containment problem – arose from a question in abstract numerical analysis. Here the goal is to construct a polytope P (not necessarily in any sense a small one) that contains C, where this requires precise specification of P s vertices. There are some sharp positive results for the case in which d=2 and C is known not to be too asymmetric, but the main result on the containment problem is negative. It asserts that when  $d \ge 3$  and the body is known only to be rotund and symmetric, there is no algorithm for the containment problem. This is the case even when there is available a certain master oracle whose question-answering power is much greater than that of C's ray-oracle. However, it turns out that even when there is no additional information about C, the following relaxation of the containment problem admits

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